



Meet the World's #1 Collaborative Robot Empowering Change in the Way Work is Done



Collaborative robots can work almost anywhere and automate almost anything



They free people up to do what they're good at: creating, collaborating, and doing something amazing.

Get an edge over your competitors with the e-Series' five key benefits

Easy Programming

87 minutes to turn anyone into a robot programmer

- Integrated Force Torque Sensor
- User friendly Teach Pendant
- Intuitive 3D interface
- Drag-and-drop functions

Fast Set-Up

The e-Series takes less than 60 minutes to unpack, mount, and program after completion of UR Academy Training

- Connects to a 110 VAC power outlet
- Intuitive user interface
- 20 industrial I/O connectors
- Ethernet connectivity
- Easy integration into almost any production set-up

Safe & Collaborative

Bridge the gap between man and machine

- Customizable stopping times + stopping distance
- Collision detection
- 17 safety functions, all EN ISO 13849-1, Cat. 3, PL. d. certified by TÜV NORD
- ISO 10218-1 Cat 3, PLd, certified by TÜV NORD

Flexible

Infinite ways of deployment and task automation

- Universal Robots+ offers plug-and-play cutting edge products
- Lightweight easy to relocate
- Mounts in any orientation
- Ability to save programming and redeploy to new tasks

Fast Payback

34 days - our fastest recorded payback worldwide

- Advanced collaborative robots available to companies of any size
- Fully upgradable software platform for a lasting and worthy investment



e-Series 3PE Teach Pendant

All e-Series cobots include the standard e-Series Teach Pendant, offering an intuitive user interface for easy programming with UR's powerful PolyScope software.

A 3-position enabling teach pendant is also available as a variant for all payloads of e-Series robots, and as a UR+ component. The 3PE device is mechanically and functionally integrated with the e-Series Teach Pendant – just Plug & Produce with any e-Series control box. Additionally, it is fully integrated into the PolyScope user interface to enable all robot motion, including Freedrive, in manual mode.

PolyScope - our intuitive programming interface

PolyScope offers users a high-level interface for very straightforward applications that any frontline operator can master. It also features a deep and complex programming environment for developers to pursue complex and experimental cobot applications.

Key Benefits

- Full mechanical 3PE device integration
- Full software integration the 3PE Teach Pendant is natively supported in PolyScope
- Connects to the control box with the same connector as the standard e-Series teach pendant
- Can be mounted to any existing e-Series teach pendant brackets
- Includes two 3PE devices, allowing comfortable use with left or right hand
- Included in TÜV NORD certifications ISO 10218-1:2011 and ISO 13849-1:2015

Hardware Specifications

Width 300 mm (11.81 in) Height 231 mm (9.09 in) Thickness 50 mm (1.97 in)

Weight, including 1 meter of cable 1.8 kg (3.961 lbs)

IP Classification IP54

R

UNIVERSAL ROBOTS

Meet the e-Series family



3 kg | 6.6 lb | Payload 500 mm | 19.7 in | Reach 5 kg | 11 lb | Payload 850 mm | 33.5 in | Reach 16 kg | 35.3 lbs Payload 900 mm | 35.4 in Reach 12.5 kg | 27.5 lbs | Payload 1300 mm | 51.2 in | Reach

Control box

Features

| IP classification | IP44 | | |
|-----------------------------|---|--|--|
| ISO 14644-1 Class Cleanroom | 6 | | |
| Ambient temperature range | 0-50°C | | |
| I/O ports | | | |
| Digital in | 16 | | |
| Digital out | 16 | | |
| Analog in | 2 | | |
| Analog out | 2 | | |
| Quadrature Digital Inputs | 4 | | |
| I/O power supply | 24V 2A | | |
| Communication | 500 Hz Control frequency Modbus TCP PROFINET Ethernet/IP USB 2.0, USB 3.0 | | |
| Power source | 100-240VAC, 47-448Hz | | |
| Humidity | 90%RH (non-condensing) | | |
| Physical | | | |
| Control box size (WxHxD) | 475 mm x 423 mm x 268 mm (18.7 in x 16.7 in x 10.6 in) | | |
| Weight | 12 kg (26.5 lbs) | | |
| Materials | Powder coated steel | | |

Teach pendant

Features

IP classification

| lumidity 90%RH (non-condensin | | | |
|---------------------------------|-------------------|--|--|
| Display resolution | 1280 x 800 pixels | | |
| Physical | | | |
| Materials | Plastic, PP | | |
| Weight including 1m of TP cable | 1.6 kg (3.5 lbs) | | |
| Cable length | 4.5 m (177.17 in) | | |
| | | | |

IP54



| | UR3e | UR5e | UR10e | UR16e | | |
|--|--|--|--|---|--|--|
| Specifications | | | | | | |
| Payload | 3 kg (6.6 lbs) | 5 kg (11 lbs) | 12.5 kg (27.5 lbs) | 16 kg (35.3 lbs) | | |
| Reach | 500 mm (19.7 in) | 850 mm (33.5 in) | 1300 mm (51.2 in) | 900 mm (35.4 in) | | |
| Degrees of freedom | — 6 rotating joints | | | | | |
| Programming | 12 inch touchscreen with polyscope graphical user interface | | | | | |
| Performance | | | | | | |
| Power, consumption, maximum average | 300 W | 570 W | 615 W | 585 W | | |
| Safety | | 17 config | urable safety functions | | | |
| Certifications | | EN ISO 13849-1, P | d Category 3, and EN ISO 10218-1 | | | |
| Force Sensing, Tool Flange Range Precision Accuracy | Force, x-y-z Torque, x-y-z 30.0 N 10.0 Nm 2.0 N 0.1 Nm 3.5 N 0.1 Nm | Force, x-y-z Torque, x 50.0 N 10.0 I 3.5 N 0.2 I 4.0 N 0.3 I | im 199.0 N 19.0 Nm km 5,0 N 9.2 Nm | Force, x-y-z Torque, 160.0 N x-y-z 5.0 N 10.0 Nm 5.5 N 0.2 Nm 0.5 Nm | | |
| Movement | | | | | | |
| Pose Repeatability per ISO 9283 | ± 0.03 mm | ± 0.03 mm | ± 0.05 mm | ± 0.05 mm | | |
| Axis movement Base Shoulder Elbow Wrist 1 Wrist 2 Wrist 3 | Working range | Working range Maximum s ± 360° ± 180° ± 180° ± 180° ± 180° ± 360° ± 180° ± 360° ± 180° ± 360° ± 180° | /s ± 360° ± 120°/s /s ± 360° ± 120°/s /s ± 360° ± 180°/s /s ± 360° ± 180°/s /s ± 360° ± 180°/s | Working range Maximum spee ± 360° ± 120°/s ± 360° ± 120°/s ± 360° ± 180°/s ± 360° ± 180°/s ± 360° ± 180°/s | | |
| Typical TCP speed | 1 m/s (39.4 in/s) | | | | | |
| Features | | | | | | |
| IP classification | IP54 | | | | | |
| ISO 14644-1 Class Clean- | | | . 5 | | | |
| Noise | Less than 60 dB(A) | Less than 65 dB(A) | Less than 65 dB(A) | Less than 65 dB(A) | | |
| Robot mounting | | A | ny Orientation | | | |
| I/O ports Digital in Digital out Analog in | | | 2 2 2 2 | | | |
| Tool I/O Power Supply Voltage | | | 12/24 V | | | |
| Tool I/O Power Supply | 600 mA | 1.5 A (Dual pin) 1 A (Sin pin) | ngle 2 A (Dual pin) 1 A (Single pin) | 2 A (Dual pin) 1 A (Single pin) | | |
| Physical | | | | | | |
| Footprint | Ø 128 mm | Ø 149 mm | Ø 190 mm | Ø 190mm | | |
| Materials | 14 | Alumi | nium, Plastic, Steel | | | |
| Tool (end-effector) connector type | M8 M8 8-pin | | | | | |
| Cable length robot arm | S- | | 6 m (236 in) | | | |
| Weight including cable | 11.2 kg (24.7 lbs) | 20.6 kg (45.4 lbs) | 33.5 kg (73.9 lbs) | 33.1 kg (73 lbs) | | |
| Operating temperature range | - | | 0-50°C | | | |
| Humidity | 90%RH (non-condensing) | | | | | |

^{*} The robot can work in a temperature range of θ -50°C at a high continuous joint speed, ambient temperature is reduced.

CERTIFIED UR+

Application Kits to Plug-and-Produce



The industry's largest ecosystem of 300+ partners and growing making 400+ UR integrated solutions

Here are just 4 examples

Palletizing

Ease-of-use is redefined with the Robotiq Palletizing Solution. Open the box, and the hardware and software is already connected and ready to install. Plan your program in just three steps, directly on the robot control device





Automated Inspection

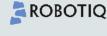
ROBOTIQ

Gocator line profile sensors use a projected laser line to perform high-resolution scanning, measurement and control for automated quality inspection, material optimization, and factory automation applications at inline production speed.

Part Feeding

The Asycube separate and orient parts on a surface by intelligent vibration. A vision system is then used to locate the parts and give the coordinates to the robot for picking.





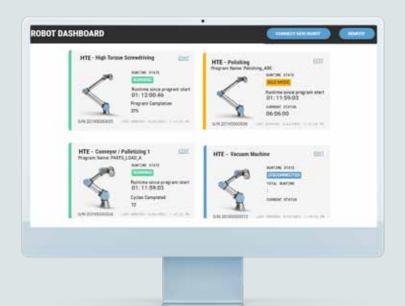


Screwdriving

The Robotiq
Screwdriving Solution,
composed of the
Robotiq Screwdriver
and Robotiq Screw
Feeder, is a robotic
peripheral designed
for industrial
applications. Its
design makes
it a unique tool
for fastening
components together
autonomously.



*Requires Annual Cobot Performance Check *Recertification required if Cobot is out of warranty



With UR INSIGHT connect the robot for visibility and analysis of daily activities.

myUR Monitoring - Track cycle times and cycle counts in real time from a smart device.

Notifications - Receive notification for robot stops, alarms and application-specific events while at the office or on the road.

Dashboard - Monitor multiple robot workcells on one dashboard and access the dashboard from any networked computer.

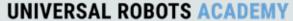
Log Report - Diagnose production inefficiencies and gain a deeper understanding through exportable/downloadable log reports.





KEY TAKE-AWAYS FROM THIS 2-DAY COURSE

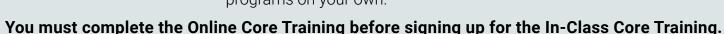
- 1. Manage the robot safely, understanding safety concepts
- 2. Build and optimize programs for several typical applications such as pick and place, palletizing, polishing or dispensing
- 3. Connect and handle peripheral equipment, such as sensors, grippers or conveyor belts
- 4. Know the online tools and resources available to help with application programming



Authorized Training Center



After the 2-day course, you will have hands-on experience with a UR robot. You will have programmed the robot several times to perform common tasks, including the operation of common peripherals (conveyors, sensors, grippers). You will be able to optimize a pick and place flow, perform palletization, understand safety concepts, and know the additional resources available to you, both online and through other training courses. You will be ready to return to your own robot and create pick and place, palletization, and other common application programs on your own.



Training is held at HTE Automation's Universal Robots Authorized Training Center unless other arrangements are made.

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